

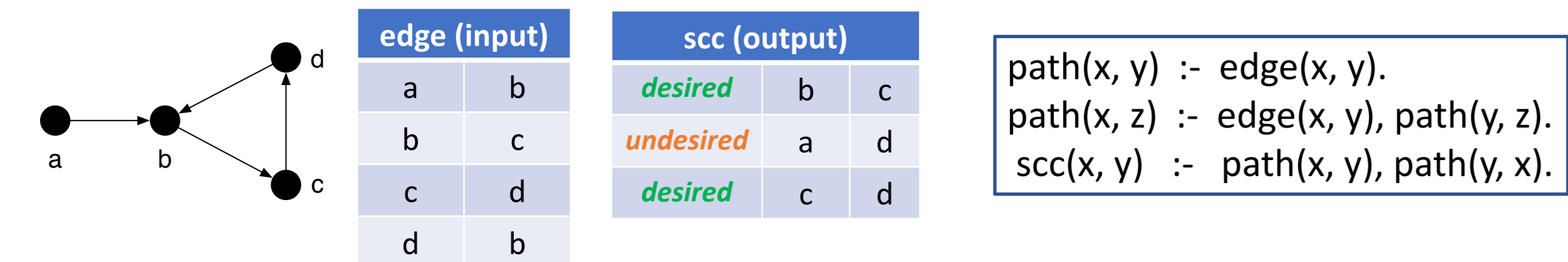
# Difflog: Synthesizing Datalog Programs using Numerical Relaxation

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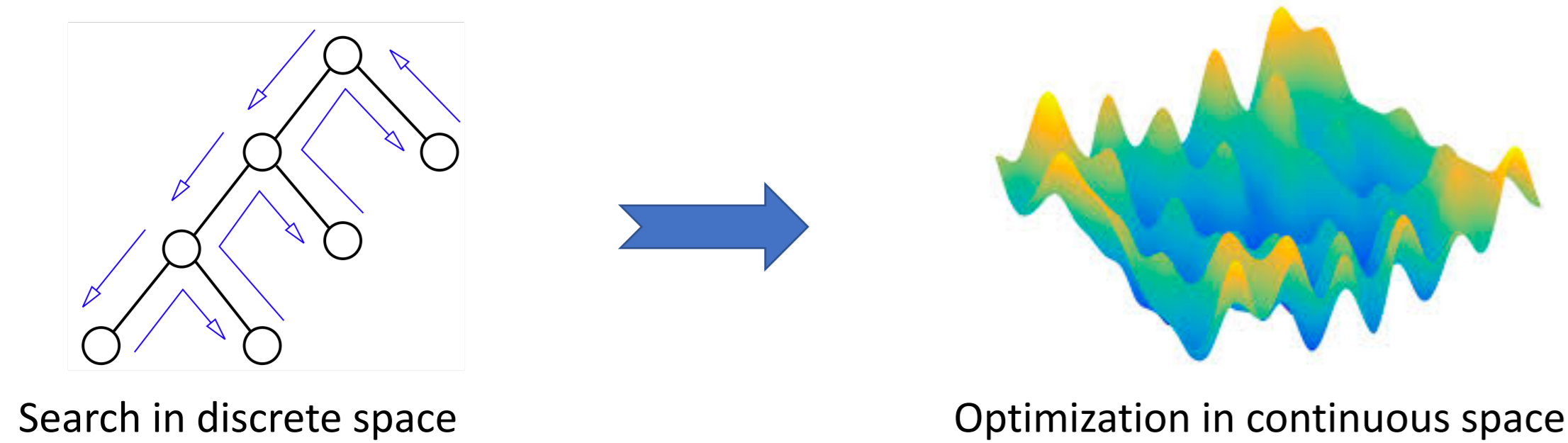


## Background and Motivation

Learning logical rules from relational input-output data



- Traditionally learned using **discrete combinatorial approaches**
- Gradient-based approaches** are remarkably successful in machine learning.
- Can gradient-based approaches greatly help to learn logical rules?**



## Importance of Learning Logic Programs

- Challenge problem in AI
- Good **interpretability** and **compositionality**
- An ideal model to represent the learned knowledge
- Logic programs widely used in many areas



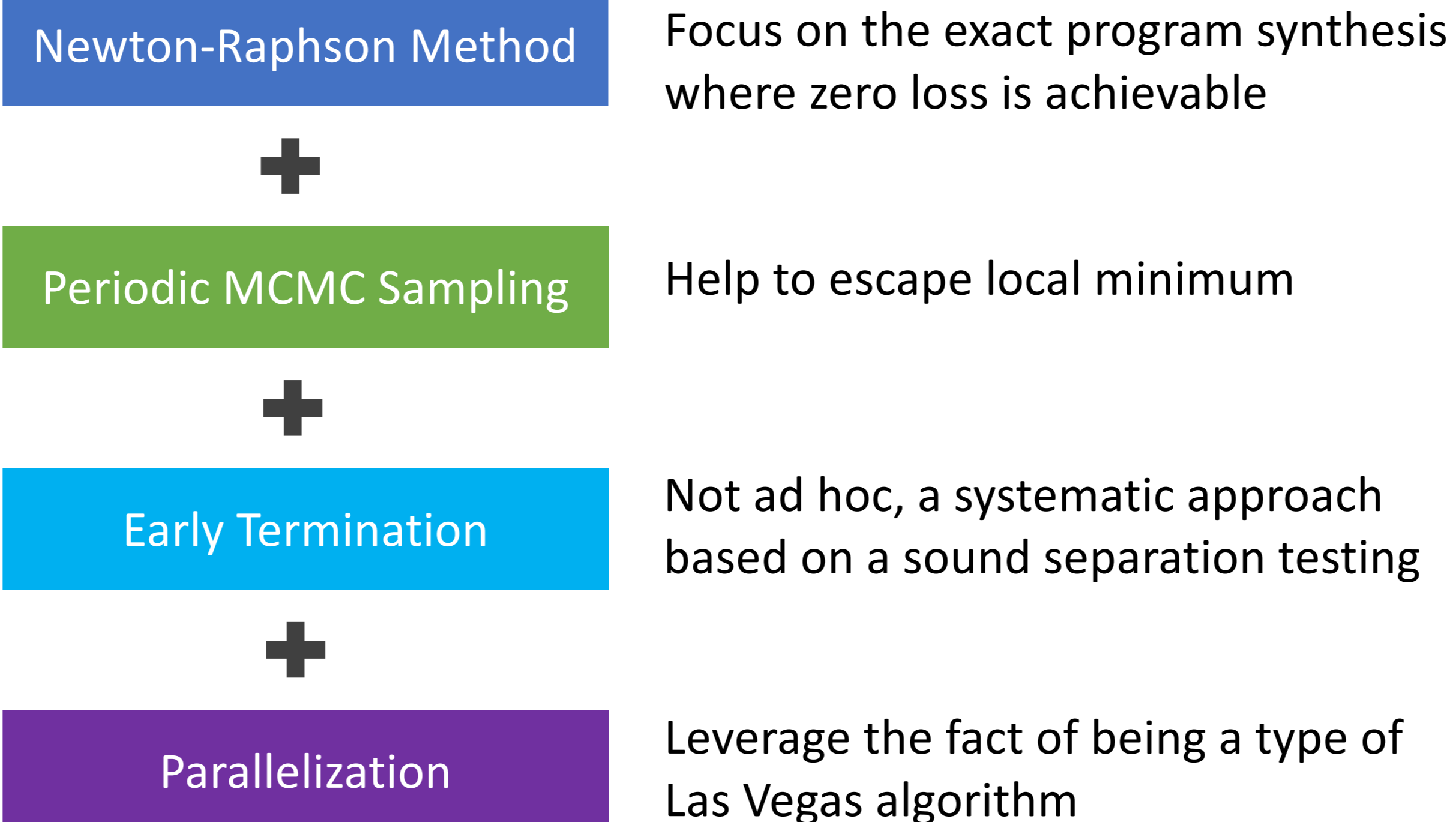
## Challenges and Our Approach

- How to **relax logical rules**?
- How to **efficiently learn** a relaxed program?
- How to **recover** classical program?

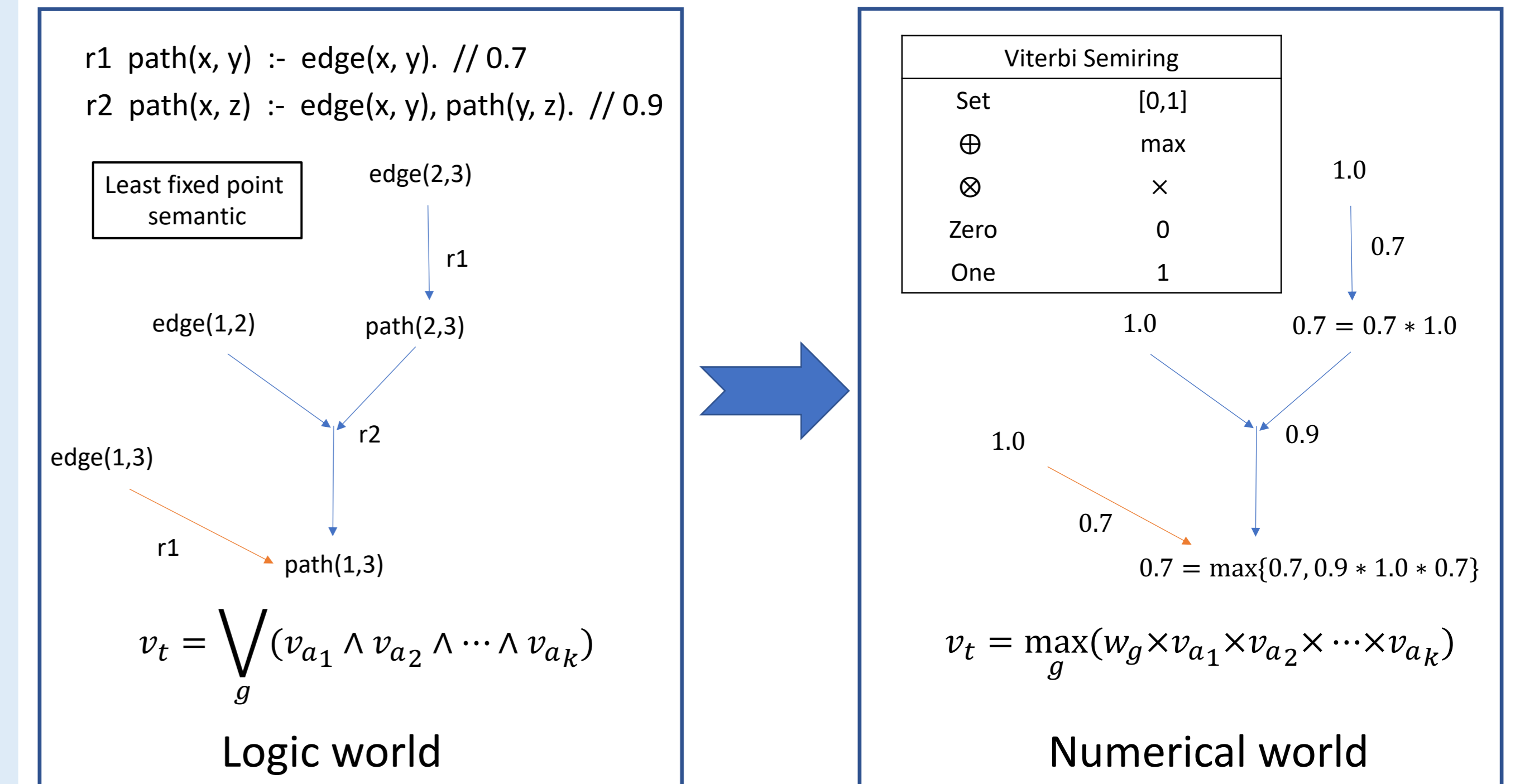
## Key Ideas

- Associate each rule with a weight
- Each tuple will get a weight (depending on how it is derived)
- Turn combinatorial search into continuous optimization
- Recover the desired logic program from the optimized weights

## Performance Optimization



## Numerical Relaxation of Logic Programs



Easy to modify existing Datalog solvers with only  $O(1)$  overhead.

$$L(w) = \sum_{t \in \text{pos}} (1 - v_t)^2 + \sum_{t \in \text{neg}} (0 - v_t)^2$$

$$w^{(i+1)} = w^{(i)} - L(w) \frac{\nabla_w L(w)}{\|\nabla_w L(w)\|^2}$$

## Connections to Classical Datalog

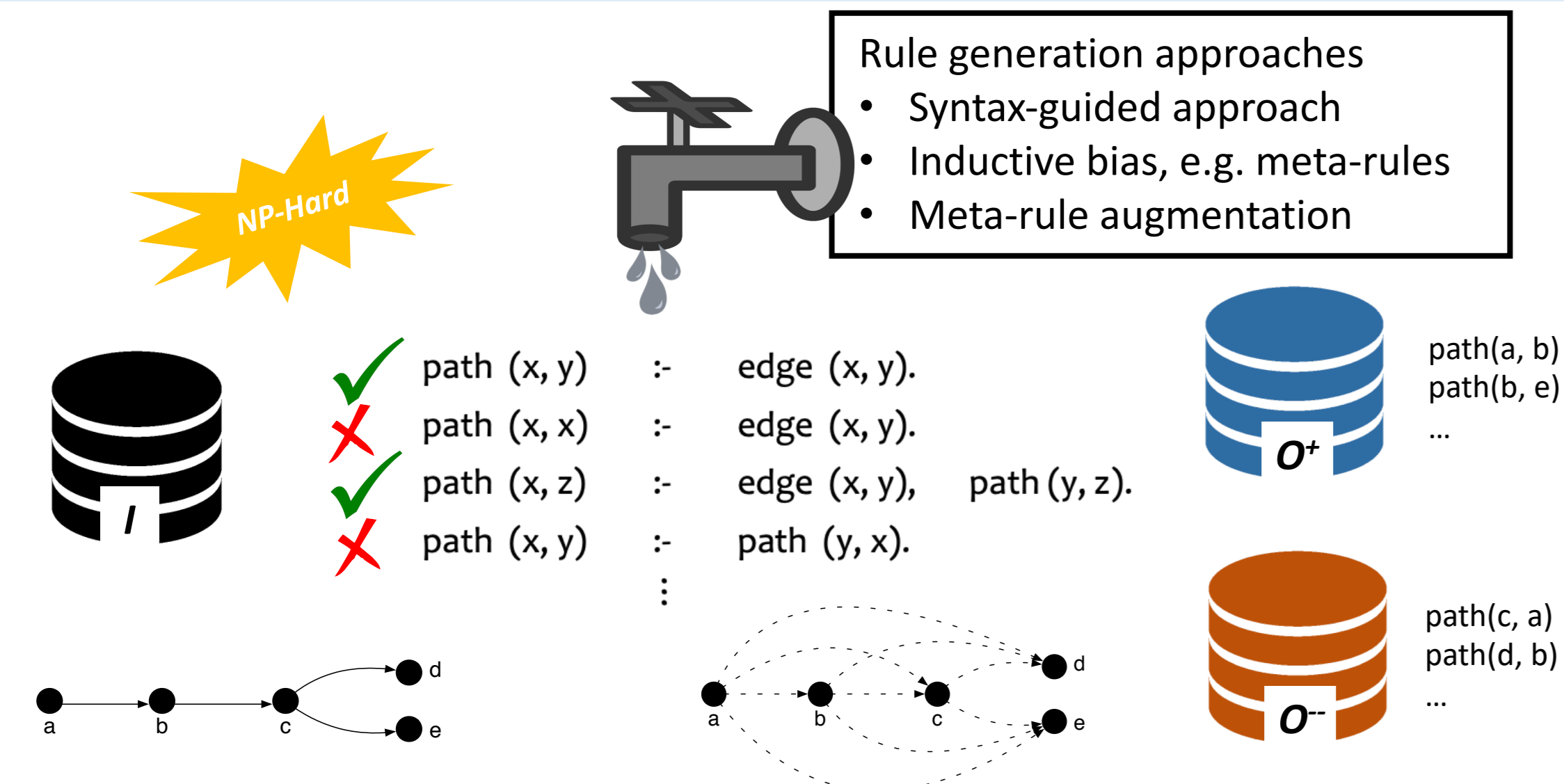
**Theorem:** Each tuple weight  $v_t$  varies continuously and monotonically increases with the rule weights  $w$ .

The loss surface is still NOT monotonic.

**Theorem:** Each tuple weight  $v_t$  is non-zero if and only if it can be derived in the classical program.

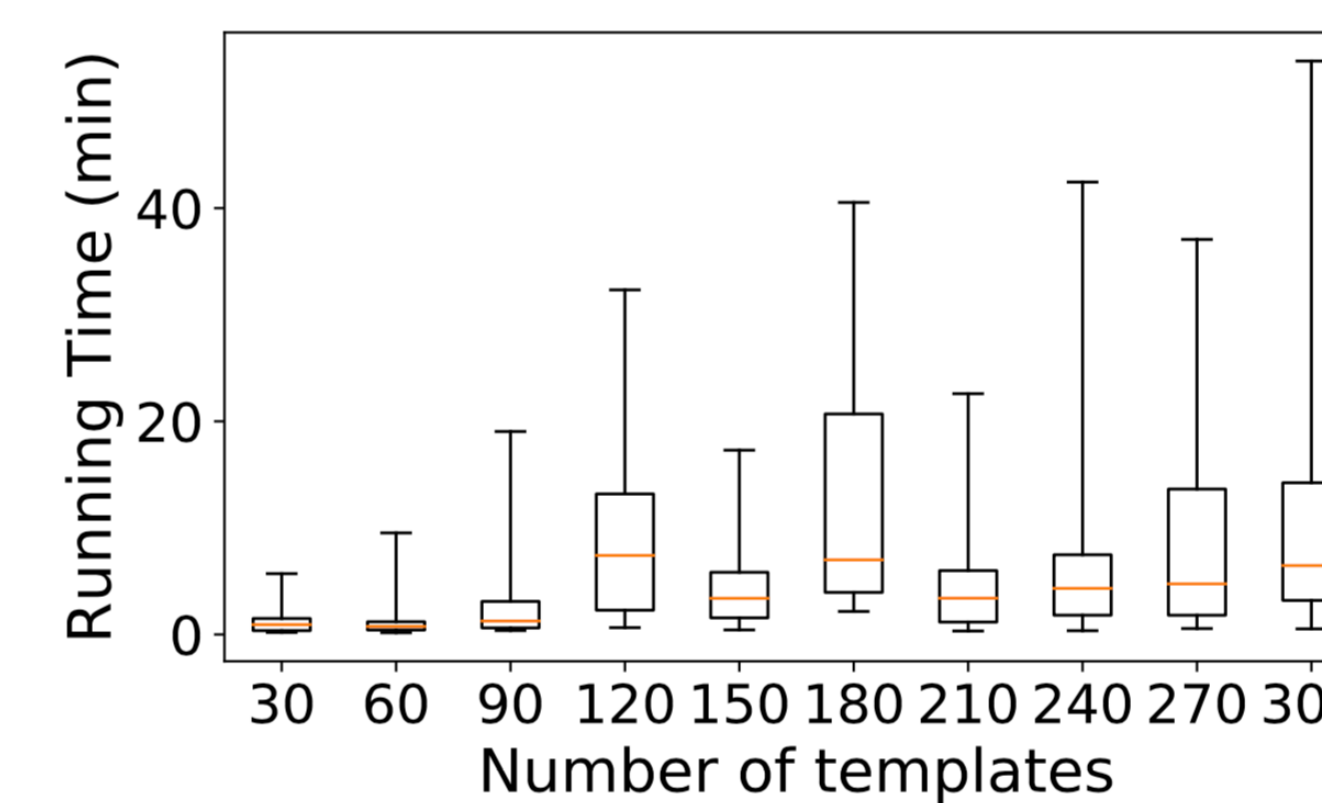
This enables us to recover classical program.

## Rule Selection Problem



## Empirical Evaluation Results

Benchmark	Rel	Rule		Tuple		DIFFLOG		ALPS	
		Exp	Cnd	In	Out	Iter	Smpl	Time	Time
polysite	6	3	552	97	27	17	1	27	84
downcast	9	4	1,267	89	175	5	1	30	1,646
rv-check	5	5	335	74	2	1,205	41	22	195
andersen	5	4	175	7	7	1	0	4	27
1-call-site	9	4	173	28	16	4	1	4	106
2-call-site	9	4	122	30	15	25	1	53	676
1-object	11	4	46	40	13	3	1	3	345
1-type	12	4	70	48	22	3	1	4	13
escape	10	6	140	13	19	2	1	1	5
modref	13	10	129	18	34	1	0	1	2,836



Significantly outperform the state-of-the-art synthesizer

Scale to a large number of templates

Benchmark	Hybrid			Newton			MCMC		
	Best	Median	Timeout	Best	Median	Timeout	Best	Median	Timeout
polysite	27s	142s	0	10s	72s	0	12s	76s	0
downcast	30s	310s	2	16s	252s	9	70s	268s	7
rv-check	22s	948s	2	N/A	N/A	32	N/A	N/A	32
andersen	4s	29s	0	3s	15s	10	4s	17s	9
1-call-site	4s	18s	0	8s	18s	1	N/A	N/A	32
2-call-site	53s	225s	0	27s	N/A	17	42s	94s	9
1-object	3s	17s	0	3s	N/A	17	N/A	N/A	32
1-type	4s	12s	0	3s	N/A	18	N/A	N/A	32
escape	1s	2s	0	1s	N/A	17	N/A	N/A	32
modref	1s	2s	0	1s	1s	4	N/A	N/A	32
<b>Total</b>			<b>4</b>			<b>125</b>			<b>217</b>

Hybrid optimization is essential to success

